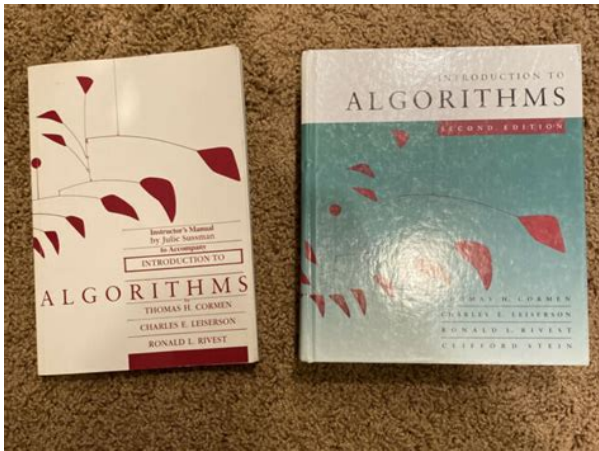


Book Descriptions:

cormen instructor manual



It contains lecture notes on the chapters and solutions to the questions. This is not a replacement for the book, you should go and buy your own copy. Note If you are being assessed on a course that\ Corrected two minor typographical errors in the lecture notes\nfor the expected height of a randomly built binary search tree. Updated the solution to Exercise 22.34b to adjust for a correc\ntion in the text. Changed the exposition of indicator random variables in\nthe Chapter 5 notes to correct for an error in the text. Corrected a typographical error in EUCLIDEANTSP on\npage 1523. That is, for most chapters we have provided a\nset of lecture notes and a set of exercise and problem solutions pertaining to the\nchapter. This organization allows you to decide how to best use the material in the\nmanual in your own course.\n\n We have not included lecture notes and solutions for every chapter, nor have we\nincluded solutions for every exercise and problem within the chapters that we have\nselected. We felt that Chapter 1 is too nontechnical to include here, and Chap\nter 10 consists of background material that often falls outside algorithms and data\nstructures courses. There are two\nreasons that we have not included solutions to all exercises and problems in the\nselected chapters. We chose this form of page numbering so that if we add\nor change solutions to exercises and problems, the only pages whose numbering is\naffected are those for the solutions for that chapter. Instead, we pass the array\nlength as a parameter to the procedure. They are written\na bit more formally than the lecture notes, though a bit less formally than the text.\nWe do not number lines of pseudocode, but we do use the length attribute on the\nassumption that you will want your students to write pseudocode as it appears in\nthe text.\n\n The index lists all the exercises and problems for which this manual provides solu\ntions, along with the number of the page on which each solution starts.<http://ganteltechnology.com/system/userfiles/financial-and-managerial-accounting-needles-solutions-manual.xml>

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Asides appear in a handful of places throughout the solutions. It enables you to typeset pseudocode in the same way that we do. Thanks also to our MIT Press editor, Bob Prior, and to David Jones of The MIT Press for help with TEX macros. Wayne Cripps, John Konkle, and Tim Tregubov provided computer support at Dartmouth, and the MIT sysadmins were Greg Shomo and Matt McKinnon. There are a few places in later chapters where we use origin indexing instead. That saves us a line of pseudocode each time. Each part shows what happens for a particular iteration with the value of j indicated. Entries in A with slashes have had their values copied to either L or R and have not had a value copied back in yet. Entries in L and R with slashes have been copied back into A . Trading a factor of n for a factor of $\lg n$ is a good deal. On small inputs, insertion sort may be faster. The procedure compares v to the array entry at the midpoint of the range and decides to eliminate half the range from further consideration. Based on the comparison of v to the middle element in the searched range, the search continues with the range halved. We can use binary search to improve the running time of the search to $\lg j$, but binary search will have no effect on the running time of moving the elements. Thus, we can restate the condition in step 5 as there exist two elements in S whose sum is exactly x if and only if the same value appears twice in the merged output.

Solutions for Chapter 2 Getting Started 219

Suppose that some value w appears twice. Steps 2, 4, 5, and 6 require $O(n)$ steps. The pairwise merging requires n work at each level, since we are still working on n elements, even if they are partitioned among sublists. The loop invariant trivially holds.

Maintenance Consider an iteration for a given value of j . Decrementing j for the next iteration maintains the invariant.

Termination The loop terminates when j reaches

i. <http://urbanmotax.nl/userfiles/financial-and-managerial-accounting-solution-manual.xml>

Instructor's Manual

by Thomas H. Cormen
to Accompany

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Third Edition

by Thomas H. Cormen
Charles E. Leiserson
Ronald L. Rivest
Cambridge, MA

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Because line 5 moves only elements that are less than key, it moves only elements that correspond to inversions. To see why, observe that the only way in which array elements change their positions is within the MERGE procedure. Moreover, since MERGE keeps elements within L in the same relative order to each other, and correspondingly for R, the only way in which two elements can change their ordering relative to each other is for the greater one to appear in L and the lesser one to appear in R. Thus, there is at least one mergeinversion involving x and y. To see that there is exactly one such mergeinversion, observe that after any call of MERGE that involves both x and y, they are in the same sorted subarray and will therefore both appear in L or both appear in R in any given call thereafter. Thus, we have proven the claim. We have shown that every inversion implies one mergeinversion. In fact, the correspondence between inversions and mergeinversions is one-to-one. Let z be the smallest value in L that is greater than y. We set counted to FALSE upon each time that a new value becomes exposed in R. Convention is to use lg within asymptotic notation, unless the base actually matters. Just as polynomials grow more slowly than exponentials, logarithms grow more slowly than polynomials. Unless the recursion tree is carefully accounted for, I do not accept it as a proof of a solution, though I certainly accept a recursion tree as a way to generate a guess for substitution method. We are given c in the recurrence, and we get to choose d as any positive constant. If we were to do a straight substitution proof, it would be rather involved. The hatcheck problem of Exercise 5.24 is a problem with lots of dependence. We omit this method from these notes.

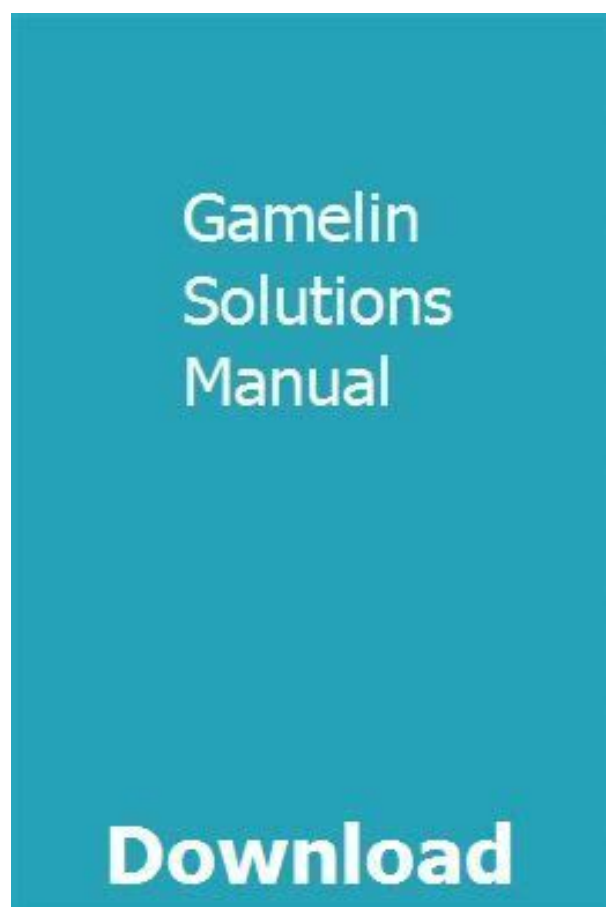
The second method is better it works in place unlike the prioritybased method, it runs in linear time without requiring sorting, and it needs fewer random bits n random numbers in the range 1 to n rather than the range 1 to n³. We view a toss as a success if it misses bin i and as a failure if it lands in bin i. In order for bin i to be empty, we need n successes in n trials. These notes will deal with maxpriority queues implemented with maxheaps. Minpriority queues are implemented with minheaps similarly. A heap gives a good compromise between fast insertion but slow extraction and vice versa. Then the maximum element is somewhere else in the subtree, possibly even at more than one location. Let m be the index at which the maximum appears the lowest such index if the maximum appears more than once. Since the maximum is not at the root of the subtree, node m

has a parent. So our assumption is false, and the claim is true.

Solution to Exercise 6.26

If you put a value at the root that is less than every value in the left and right subtrees, then MAXHEAPIFY will be called recursively until a leaf is reached. To make the recursive calls traverse the longest path to a leaf, choose values that make MAXHEAPIFY always recurse on the left child. With such values, MAXHEAPIFY will be called h times where h is the heap height, which is the number of edges in the longest path from the root to a leaf, so its running time will be h since each call does $O(1)$ work, which is $O(\lg n)$. Thus if n is odd, x is even, and if n is even, x is odd.

To prove the base case, we must consider separately the case in which n is even x is odd and the case in which n is odd x is even. Observe that we would also increase the number of leaves by 1, since we added a node to a parent that already had a child.



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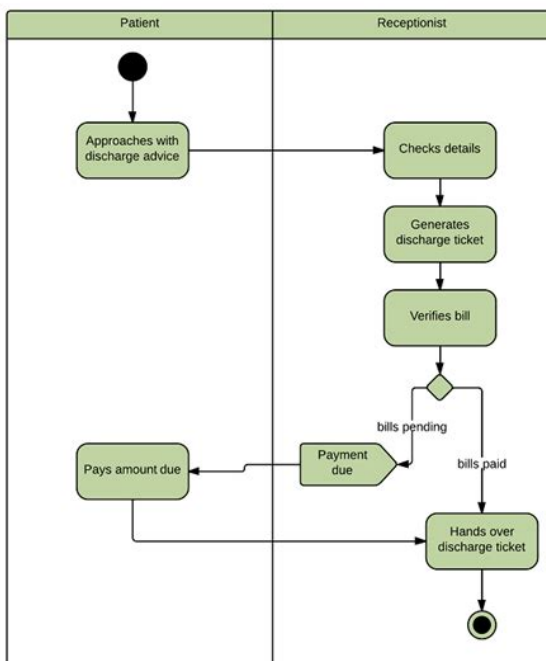
For a lower bound of $\Omega(n \lg n)$, consider the case in which the input array is given in strictly increasing order. Each call to MAXHEAPINSERT causes HEAPINCREASEKEY to go all the way up to the root. The change needed to support d ary heaps is in MAXHEAPIFY, which must compare the argument node to all d children instead of just 2 children. Increasing an element may make it larger than its parent, in which case it must be moved higher up in the tree. This can be done just as for insertion, traversing a path from the increased node toward the root. Since the array size is reduced by at least half on each recursive call, the number of recursive calls, and hence the stack depth, is $O(\lg n)$ in the worst case. This was not what we are asked to prove; we cannot introduce any extra assumptions.

810 Solutions for Chapter 8 Sorting in Linear Time

Now, consider the decision tree of height h for any comparison sort for S . Since the elements of each subsequence can be in any order, any of the k .

When comparing two elements, compare them by their values and break ties by their indices. For n elements, their indices are $1 \dots n$. Each can be written in $\lg n$ bits, so together they take $O(\lg n)$ additional space. Additional time requirements The worst case is when all elements are equal. Since A is a deterministic algorithm, it must always reach the same leaf when given a particular permutation as input, so at most $n!$. Therefore exactly $n!$. That is, we can assume that TA consists of only the $n!$. The number of passes, d , would have to be the number of digits in the largest integer. We assume that the range of a single digit is constant. Since the strings have varying lengths, however, we have to pad out all strings that are shorter than the longest string. Analyzing the running time is a bit trickier.

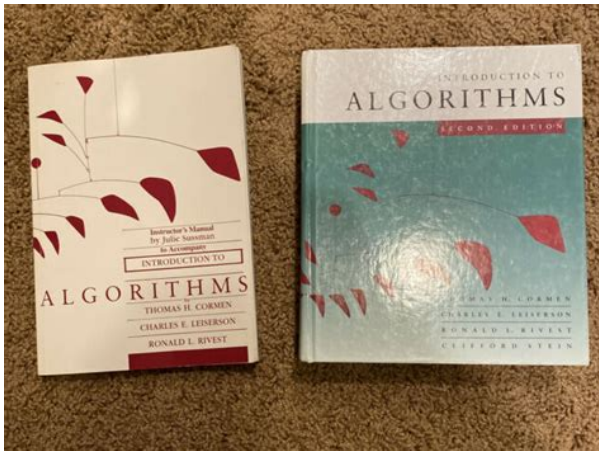
<https://pazayac.com/images/93-mercury-villager-repair-manual.pdf>



Let us count the number of times that each string is sorted by a call of counting sort. Suppose that the i th string, s_i , has length l_i . Since there are n red jugs and n blue jugs, that will take n^2 comparisons in the worst case. To solve the problem, an algorithm has to perform a series of comparisons until it has enough information to determine the matching. We can view the computation of the algorithm in terms of a decision tree. Every internal node is labeled with two jugs one red, one blue which we compare, and has three outgoing edges red jug smaller, same size, or larger than the blue jug. The leaves are labeled with a unique matching of jugs. Solutions for Chapter 8 Sorting in Linear Time 817 The height of the decision tree is equal to the worstcase number of comparisons the algorithm has to make to determine the matching. Every tree with a branching factor of 3 every inner node has at most three children has at most 3^h leaves. Since the decision tree must have at least $n!$. The numbers are arbitrary and do not correspond to the volumes of jugs, but are just used to refer to the jugs in the algorithm description. It eventually must reach 0 or 1, in which case the recursion terminates. What about the running time. Because it is randomized, no particular input brings out the worstcase behavior consistently. The running time of RANDOMIZEDSELECT is a random variable that we denote by T_n . To show this more formally, draw a binary tree of the comparisons the algorithm does. The n numbers are the leaves, and each number that came out smaller in a comparison is the parent of the two numbers that were compared. So the second smallest is among

the elements that were compared with the smallest during the tournament. Observe also that the On term in the recurrence is really n , since the partitioning in step 4 takes n not just $O(n)$ time.

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In each case, we will start out with the pipeline at a particular y coordinate and see what happens when we move it. Let us start with the pipeline somewhere on or between the two oil wells whose y coordinates are the lower and upper medians. A symmetric argument shows that if we start with the pipeline going through the oil well whose y coordinate is the lower median and move it down, then the total spur length increases. We see, therefore, that when n is even, an optimal placement of the pipeline is anywhere on or between the two medians. Now we consider the case when n is odd. Build the heap using BUILDHEAP, which takes n time, then call HEAPEXTRACTMAX i times to get the i largest elements, in $i \lg n$ worstcase time, and store them in reverse order of extraction in the output array. Partition around that number in n time. Otherwise, we proceed as follows. We then compute the total weights of the two halves. Let y be any point real number other than x . Then he could choose keys that all hash to the same slot, giving worstcase behavior. 1110 Lecture Notes for Chapter 11 Hash Tables One way to defeat the adversary is to use a different hash function each time. You choose one at random at the beginning of your program. One can prove this property formally, but informally, consider that both heapsort and quicksort work by interchanging pairs of elements and that they have to be able to produce any permutation of their input array. Suppose that we move an element from an underloaded value j to an overloaded value k , and we leave all other elements alone. Thus, running time is $O(h)$, where h is the height of the tree. Insertion and deletion Insertion and deletion allows the dynamic set represented by a binary search tree to change. The binarysearchtree property must hold after the change. Result $A \ D \ B \ K \ H \ F \ C$ Time Same as TREESUCCESSOR.

In a heap, the largest element smaller than the node could be in either subtree. Note that if the heap property could be used to print the keys in sorted order in $O(n)$ time, we would have an $O(n)$ time algorithm for sorting, because building the heap takes only $O(n)$ time. But we know Chapter 8 that a comparison sort must take $n \lg n$ time. Solution to Exercise 12.25 Let x be a node with two children. Procedure TREESUCCESSOR traverses an upward path to u from the maximum element which has no right subtree in the subtree rooted at v . TREESUCCESSOR traverses a path up the tree to an element after u , since u was already printed. Then there exists a path from the root to a node at depth h , and the depths of the nodes on this path are $0, 1, \dots, h$. Let P be the set of nodes on this path and Q be all other nodes. It is just like INORDERTREEWALK it prints the current node and calls itself recursively on the left and right subtrees, so it takes time proportional

to the number of nodes in the tree. We use the substitution method. Observe that once an element x is chosen as the root of a subtree T , all elements that will be inserted after x into T will be compared to x . Similarly, observe that once an element y is chosen as the pivot in a subarray S , all other elements in S will be compared to y . This set of lecture notes is intended as a refresher for the students, bearing in mind that some time may have passed since they last saw redblack trees. The procedures in this chapter are rather long sequences of pseudocode. Hence, property 4 is OK. When we start the loop body, the only violation is of property 4. There are 6 cases, 3 of which are symmetric to the other 3. The cases are not mutually exclusive. In the shortest path, at most every node is black. Since the two paths contain equal numbers of black nodes, the length of the longest path is at most twice the length of the shortest path.

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We can say this more precisely, as follows. Since every path contains bh/x black nodes, even the shortest path from x to a descendant leaf has length at least bh/x . Moreover, if there are any nodes not on the right spine, then at least none such node has a parent on the right spine. To see why, observe that the children of the root would change to point to the new root, then their children would change to point to them, and so on. Since there are n nodes, this change would cause insertion to create n new nodes and to take n time. From parts a and c, we know that insertion into a persistent binary search tree of height h , like insertion into an ordinary binary search tree, takes worst case time $O(h)$. We need to show that if the redblack tree is persistent, insertion can still be done in $O(\lg n)$ time. Make the same changes to RBINSERT as we made to TREEINSERT for persistence. As RBINSERTFIXUP moves up the stack of parents, it needs only parent pointers that are at known locations a constant distance away in the stack. But to do so without using parent pointers we need to walk down the tree to the node to be deleted, to build up a stack of parents as discussed above for insertion. Erica Lin, Ronald L. Rivest, Clifford Stein, Cambridge, Massachusetts; London, England; Boston Burr Ridge, IL; Dubuque, IA; Madison, WI; New York; San Francisco; St. Louis; Montreal; Toronto; Instructor's Manual Inc., 1221 Avenue of the Americas, New York, NY 10020. Technology and The McGraw-Hill Companies, Inc. All rights reserved. Because this revision affected chapters Chapter 3, Chapters 5, 11, 12, 16, 17, 21, and 26; index. Affected chapters Chapter 3, Chapters 5, 11, 12, 16, 17, 21, and 26; index. Affected pages 54. Second Edition, by Thomas H. Cormen, Charles E. Leiserson, Ronald L.

Rivest, That is, for most chapters we have provided a There are two. Second, if we were to include all solutions, this manual would be longer than the The PP numbers restart from 1 at the beginning of each. We chose this form of page numbering so that if we add. Moreover, if we add material. In some places, we have simplified the material for. Some sections of the. If you are projecting a present. We find them inconvenient to. Instead, we pass the array. This change makes the pseudocode. They are written. We do not number lines of pseudocode, but we do use the length attribute on the. Also, we are less. Preface P3. You can find this package. Please report errors by. You can use the MIT. Press web site for the text, to Julie Sussman, P.P.A. Julie did such a superb job on the rst edition manual, nd Charles Leiser, Rivest, and Cliff Stein—provided helpful comments and suggestions for solutions. At this point, we do not know which TAs wrote which solutions, and so we simply. Wayne Cripps, John Konkle, and Tim Tregubov provided computer support at Dartmouth, and the. MIT sysadmins were Greg Shomo and Matt McKinnon. Phillip Meek of McGraw. Hill helped us hook this manual into their web site. July 2002 Lecture Notes for Chapter 2. Getting Started. The sequences are typically stored in arrays. Along with each key may be additional. Each way will be expressed. If you know any of these. Software. Therefore, unlike. There are a few places in. If you are translating. One option is to adjust all index calculations. An easier option is, when using an. That saves us a line of pseu. Lecture Notes for Chapter 2 Getting Started 23. We'll put in the. The heavy vertical lines. Rather than getting

bogged down in another loop. At that point, the value of key is placed into this position. Saves space and writing time. We assume that if x and y denote objects, then it does not. Usually, running time. No concurrent operations.

Like the size n of the array being. If multiplying two integers, could be the total. For example, graph algorithm. Example "sort the points by x coordinate." These vary according to the input. Lecture Notes for Chapter 2 Getting Started 27. For example, when search. Because it's often about as bad as the worst. Although the average case running time is approximately half of the worst case. Drop lower order terms an 2 . Ignore constant coefficient n^2 . But we cannot say that the worst case running time $T(n)$ equals n^2 . Lecture Notes for Chapter 2 Getting Started 29. Its worst case running time has MERGE A, p, q, r . Combine. But it is common to see students perform. We will use this technique when we. Lecture Notes for Chapter 2 Getting Started 211. Entries in L and R with slashes have. The last part shows that the subarrays are merged back. The last for. Total time n . Lecture Notes for Chapter 2 Getting Started 213. When n^2 , time for merge sort steps. But for large enough inputs, merge. It's not worth going into this. Getting Started. The algorithm maintains the loop invariant that at the start of each iteration of the. After the r st $n-1$. The best case running time is. Then. The procedure com. We give both iterative and recursive versions. The initial call to either version should have. The recurrence for these procedures is therefore. We can use binary search. Therefore, binary search alone. Thus, we can restate the. Solutions for Chapter 2 Getting Started 219. Then w appeared once in S and once. Conversely, suppose that there are values w, y . Steps 2, 4, 5, and 6 require $O(n)$ steps. Thus. The pairwise. The number of levels. Therefore, the total running time for the merging is. The largest asymptotic value. To see why, r st observe that k cannot be more than $\lg n$ i.e., it can't have. By the loop in.

Decrementing j for the next. By the statement of the. By the loop invari. Solutions for Chapter 2 Getting Started 221. The worst case. Line 8 will eventually drop key to the left of this element, thus eliminating the. In other words, each iteration of. We claim that if we were to run merge sort, there would be exactly one merge. To see why, observe that the only way in which a r. Moreover, 222. Solutions for Chapter 2 Getting Started. Thus, there is at least one merge. Inversion involving. In fact, the. And since x is in L and y is in R , x must be within a subarray preceding the. Therefore x started out in a position i preceding y 's. Let z be the smallest value in L . At some point during the merging process, z and y will. Therefore, we need to detect the r st time. The following pseudocode, modeled on merge sort, works as we have just de. We count them the r st time. Since we have added only a constant amount of additional work to each pro. Growth of Functions. We're studying asymptotic. Examples of functions in $O(n^2)$. Examples of functions in n^2 . Can chain together. Same for $O(n)$, $o(n)$, and $\Theta(n)$. Same for O and Θ . No trichotomy. Although intuitively, we can liken O to Θ , to Ω , etc., unlike. A surprisingly useful inequality for all real x . In the expression $\log_b a$. Can use Stirling's approximation. Let's define the function. Similarly, since for any particular n , $h(n)$ is the larger of $f(n)$ and $g(n)$, we have for. Note that $T(n) = O(n^2)$ means that $T(n)$. This statement holds for any running time $T(n)$. Proving that a function $f(n)$ is polynomially bounded is equivalent to proving that. In the following proofs, we will make use of the following two facts. Substitute $\lg n$ for n , 2 for b , and 1 for a , giving. Recurrences. Unless the recursion tree is carefully. I find that it is too easy to make an error in paren. Might need to use dif. We are given c in the. It's OK for d to. Guess $T(n) = dn^3$. Then verify by substitution method. For upper bound, rewrite as $T(n)$. By summing across each level, the recursion tree shows the cost at each level of. Based on the master theorem Theorem 4.1.

Check regularity condition don't really need to since $f(n)$ is a polynomial. We sometimes prove. Recurrences. Since the values at. This recurrence can be similarly solved. To prove the upper bound, the regularity condition is. This is a divide and conquer recurrence with. This is another divide and conquer. This is a divide and conquer recurrence. Since. The inductive hypothesis. The easy way to do this is with a change of variables, as on page 66. If we were to do. Instead, we will

show that, we will have that. For the upper bound of T_n . The upper bound of T_n . Solutions for Chapter 4 Recurrences 413 Our inductive To prove the upper bound, we will show that Our inductive Equivalently, We assume that $n \geq 4$, which implies that Lecture Notes for Chapter 5. Probabilistic Analysis and Randomized Algorithms In other words, if the X_H counts the number of heads In fact, this is what the book does Lecture Notes for Chapter 5 Probabilistic Analysis and Randomized Algorithms 55 Thus, the expected hiring cost is $O(n \ln n)$, which is much better than the worst Example 1, 2, 3, Example any ordering in which HIREASSISTANT n We omit this method The algorithm chooses x_i randomly from the n . Probabilistic Analysis and Randomized Algorithms BIASED RANDOM twice. Repeatedly do so until the two calls return different Since there is no other way for UNBIASED RANDOM to return a value, it returns 0 UNBIASED RANDOM is linear in the expected number of iterations. We can view This event occurs when cand_i This event occurs precisely when the list of ranks Our n al event is A , which occurs when HIREASSISTANT hires exactly twice. Noting that the events E_1, E_2, \dots, E_n are disjoint, we have This would be a painstaking Thus, Thus, we can use Let X be the the random variable denoting the total number of inverted pairs in the The loop invariant becomes The initialization part For example, consider That would mean that each permutation Thus, once offset is determined, so is the entire permutation.

Since each value of Thus, n permutations occur with We define a random vari. Thus, We have n independent Bernoulli trials, Using a binomial distribution, therefore, we have that As before, we find that By linearity of E the counter increases due to this INCREASE Since we can ignore values of C_j Thus, by equation C.26, Heapsort Here, we bypass these attributes and There is no significance to whether an arc is drawn above or Similar argument for minheaps. It is used to maintain The way MAXHEAPIFY works If we hit a leaf, then the subtree rooted at the leaf is In this case, the maxheap is a leaf. Decrementing i reestablishes the loop invariant at each iteration. By the loop invariant, each node, HEAPIFY instead of MAXHEAPIFY, also taking linear time. MAXHEAPIFY $A, 1, i-1$ These notes will deal with max Minpriority queues are implemented Lecture Notes for Chapter 6 Heapsort 67 MAXHEAPIFY $A, 1, n-1$ remakes heap Solutions for Chapter 6. Heapsort Then the maximum element is somewhere else in the subtree Let m be the index at which the Since the maximum is not at the root of the subtree, node m has a parent. Since But by the max To Solutions for Chapter 6 Heapsort 611 MAXHEAPIFY always recurse on the left child. It follows the left branch when the With such values, MAXHEAPIFY will be called h Since we have a case in which MAXHEAPIFY's running For example, although all The tree leaves nodes at height 0 are at depths H and $H-1$. They consist of. Let x be the number of nodes at depth H —that is, the number of nodes in the Thus if n is odd, x is even, and if n is even, x is odd. Here are two ways to do Observe that we would also increase the Let n_h be the number of nodes at height h in the n node tree T . Solutions for Chapter 6 Heapsort 613 Consider the following For a lower bound of Solutions for Chapter 6 Heapsort 615 Since the depth of node i is $\lg i$ DARY PARENT i . DARY CHILD i, j . To convince yourself that these procedures really work, verify that The change needed to support d ary heaps is in MAX.

HEAPIFY, which must compare the argument node to all d children instead of The worst case running time is still h , where h This can be done just as for insertion, travers In the worst case, the DARY HEAP INCREASE KEY A, i, k Quicksort Lecture Notes for Chapter 7 Quicksort 73 This is done by swapping the pivot and the r st Instead, randomly pick an element from the Thus, the worst case Lecture Notes for Chapter 7 Quicksort 77 We will now compute a bound on the overall number of comparisons. Thus, the probability that any particular one of them is the r st one chosen is Quicksort Similarly, maximum depth corresponds to always taking the larger part of the par The maximum. All these equations are approximate because we are ignoring floors and ceilings. What randomization can do We have the recurrence Substituting this guess into the QUICKSORT and QUICKSORT. This executes the same operations as calling The sequence of recursive calls in this QUICKSORT calls QUICKSORT again with almost the same range. To avoid The following variation of QUICKSORT checks Section 7.1. The expected running time is not affected, because

exactly the same work is Sorting in Linear Time There are $n!$ leaves, because every In other words Lecture Notes for Chapter 8 Sorting in Linear Time 83 Each leaf becomes parent to two new Counting sort is stable keys with same value appear in same order in output as How big a k is practical Punch card readers for census tabulation in early It's the algorithm for The stable sort on digit i leaves them in the right How to break each key into digits Choosing $r \lg n$ gives us Compare radix sort to merge sort and quicksort BUCKETSORT A, n Assume without loss of generality that On sort time for all buckets. Because insertion sort runs in quadratic time, bucket sort time is Used a function of key values to index into an Solutions for Chapter 8. Sorting in Linear Time We have $2 \lg m$, which gives us $\lg m$. For all the possible m 's given here.

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